

1 **A measure of competitive access to destinations for comparing**
2 **across multiple study regions**

3 **Jeff Allen**

4 Department of Geography and Planning, University of Toronto St. George
5 100 St. George St., Toronto, Ontario M5S 3G3, Canada
6 jeff.allen@utoronto.ca

7 **Steven Farber**

8 Department of Human Geography, University of Toronto Scarborough
9 1265 Military Trail, Toronto, Ontario, M1C 1A4, Canada
10 steven.farber@utoronto.ca

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15 **Abstract**

16 Accessibility is now a common way to measure the benefits provided by transportation-land use
17 systems. Despite its widespread use, few measurement options allow for the comparison of acces-
18 sibility across multiple urban systems, and most do not adequately control for market competition
19 between demand-side actors and supply-side facilities in localized markets. In this paper we develop
20 a measure of competitive access to destinations that can be used to accurately compare accessi-
21 bility between regions. This measure stems from spatial interaction modelling and accounts for
22 competition at both the supply and demand sides of analysis, regional differences in transportation
23 networks and travel behaviour, and any imbalance between the size of the population and the
24 number of opportunities. We use this method to compute access to employment for Canada's eight
25 largest cities to comparatively examine inequalities in accessibility, both within and between cities,
26 and by travel mode.

1 Introduction

2 Accessibility, from an urban geography perspective, is typically understood as the potential for
3 interaction or ease of reaching destinations (Hansen, 1959). Accessibility is a function of transport
4 networks, land use characteristics (e.g. one's location in relation to the distribution of destinations),
5 as well as individual social and economic factors (e.g. can someone afford a car) (Handy & Niemeier,
6 1997; Kwan, 1998; Geurs & Van Wee, 2004). Accessibility measures have been used in a wide range
7 of studies analyzing their effect on activity participation rates (e.g. Paez et al., 2009), employment
8 outcomes (e.g. Merlin & Hu, 2017), commuting times (e.g. Kawabata & Shen, 2007), as well as
9 in normative studies analyzing inequalities between neighbourhoods and population groups (e.g.
10 Delbosc & Currie, 2011), examining changes in accessibility over time (e.g. Farber & Fu, 2017), or
11 comparing levels of access by different travel modes (e.g. Benenson et al., 2011).

12 Despite the quantity of research on accessibility, there are only a few studies that compare
13 accessibility between different cities. One reason for this is the difficulty in generating accessibility
14 metrics which can be used to meaningfully compare between regions which have different quanti-
15 ties and distributions of populations, opportunities, and transport networks. Existing multi-city
16 studies tend to use non-competitive measures (Kawabata & Shen, 2006; Grengs et al., 2010; Levine
17 et al., 2012; Owen & Levinson, 2014; Deboosere & El-Geneidy, 2018), which sum the number of
18 opportunities (e.g. jobs) that can be reached from a location. However, the raw values of acces-
19 sibility computed for locations in one region are not a meaningful comparator to access scores in
20 another region in situations where there are capacity constraints at the destination (e.g. like access
21 to employment where each job can only be filled by one worker). This is because the accumulation
22 of supply is not adequately discounted for the amount of demand it is servicing. For example,
23 central Toronto may have tenfold the amount of nearby jobs than central Winnipeg, but if the
24 nearby labour force is ten times the size, then access should be approximately equivalent as there
25 is an equal number of accessible jobs per worker.

26 Accordingly, the objective of this paper is to develop a measure of access to destinations that
27 accounts for competition and can be used to compare between regions. Specifically, this measure
28 accounts for competition at both the supply and demand sides of analysis, similar to the balancing
29 factors of a doubly-constrained spatial interaction model (e.g. Geurs & van Eck, 2003; Horner,
30 2004). It also accounts for regional specific transportation networks and travel behaviour as well as
31 differing imbalances between the size of the population and the number of available opportunities.
32 We apply this method to computing access to employment for Canada's eight largest urban regions.
33 We exemplify its use by analyzing spatial inequalities of accessibility within and between regions
34 as well as by travel mode. The data and methods used are all open-source, so they can be shared
35 and replicated with minimal cost (<https://github.com/SAUSy-Lab/canada-transit-access>).

2 Competitive Accessibility

At a basic level, measuring accessibility is concerned with evaluating how well a city's land use and transportation system provides people with the opportunity to travel to a broad spectrum of destinations in a reasonable amount of time. Methodologically, there are a number of ways in which accessibility has been measured in research and practice (Handy & Niemeier, 1997; Geurs & Van Wee, 2004). Accessibility measures are typically either place-based (linked to an area or a specific point in space) or person-based (linked to an individual, often through their daily activity patterns) (Miller, 2007). Probably the most common form of measuring place-based access to destination metrics are integral, they sum opportunities that can be reached from specific location(s) in space (Handy & Niemeier, 1997; Kwan, 1998). These are typically formulated as follows:

$$A_i = \sum_{j=1}^J O_j f(t_{i,j}) \quad (1)$$

Where A_i is the measure of access for a location i . O_j is the number of opportunities at a location j . O_j can be interpreted as the attractiveness, or gravitational pull, at location j . $f(t_{i,j})$ is a decreasing function of travel cost, t , from i to j . $t_{i,j}$ is based on one or more impedance factors like travel time or monetary cost. The simplest form of $f(t_{i,j})$ is a threshold indicator, which returns a 0 or 1 whether or not the travel time is less than a threshold. In this case, A_i is interpreted as the number of opportunities (e.g. jobs) that can be reached within a set travel time (e.g. within 30 minutes). Gravity models extend this by using a decay function to weight nearby destinations more than destinations that are further away. However, measures computed by (1) are most suitable for analyzing access to destinations where there is no competition for resources at the destination (i.e. for situations where being able to access an opportunity is not dependent on other people accessing it as well).

Equation (1) can be expanded in order to incorporate competition for resources at the destination (Weibull, 1976). This has been commonly used in measuring access to health services, often formulated as floating-catchment approaches, to output accessibility measures as intuitive metrics like doctors per person (Luo & Wang, 2003; Delamater, 2013). Applied to access to employment, competitive measures can account for how employment opportunities and the labour force are both spatially distributed and overlapping, and that competition exists among the labour force for jobs (Shen, 1998; Geurs & van Eck, 2003; Kawabata & Shen, 2006). Mathematically, this involves normalizing opportunities at j by the population within their catchment area, L_j .

$$A_i = \sum_{j=1}^J \frac{O_j f(t_{i,j})}{L_j} \quad L_j = \sum_{i=1}^I P_i f(t_{i,j}) \quad (2)$$

Where P_i is the population at i competing for opportunities. In research on access to health services, this metric has been simplified by setting $f(t_{i,j})$ to an indicator function to generate population to

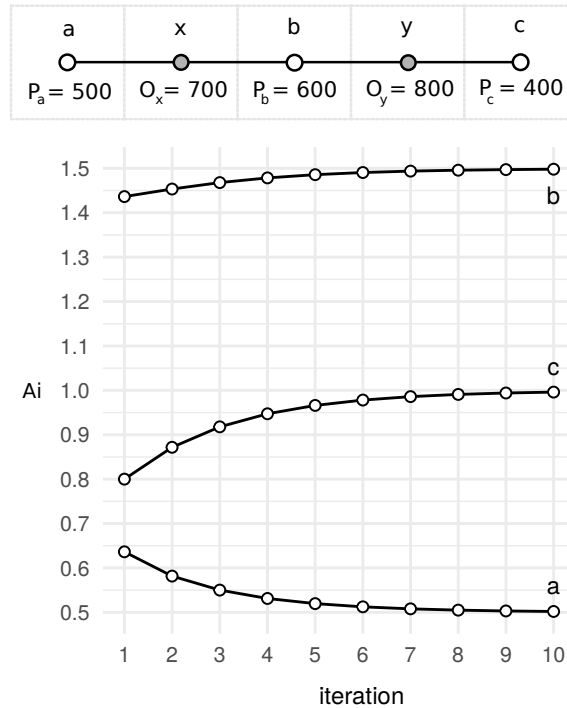
1 provider ratios (these are commonly referred to as 2-step floating catchment area measures) (Luo
2 & Wang, 2003; Delamater, 2013).

3 This can be expanded to account for competition at both the origin and destination locations
4 by incorporating A_i into the equation for L_j to normalize for the number of opportunities that
5 someone at location, i , can reach.

$$A_i = \sum_{j=1}^J \frac{O_j f(t_{i,j})}{L_j} \quad L_j = \sum_{i=1}^I \frac{P_i f(t_{i,j})}{A_i} \quad (3)$$

6 This form is akin to a doubly constrained spatial interaction model, where balancing factors
7 are used to ensure that the sum of flows from i and destined to j equals the observed amount
8 arriving and departing from each zone (Wilson, 1971; Fotheringham & O’Kelly, 1989). A_i and
9 L_j are simply the inverse of the balancing factors in the doubly constrained model. Since L_j and
10 A_i are mutually dependent, they have to be estimated iteratively until they reach convergence.
11 Convergence is guaranteed if $\sum O_j = \sum P_i$ (e.g. if the labour force is equal to the number
12 of employment opportunities). Figure 1 shows, for a simplistic linear city, how the measure of
13 competitive accessibility in (3) converges after several iterations.

Figure 1: Iterative convergence of competitive accessibility for a simple linear city



14 The equations in (3) are particularly relevant for analyzing access to employment. Employers
15 compete for workers who have varying levels of access to jobs, and people compete for jobs at

1 locations which have varying levels of access to the labour force (Geurs & van Eck, 2003; Horner,
 2 2004; Merlin & Hu, 2017). This type of measure has been applied at a regional scale in Sardinia
 3 (De Montis et al., 2011; Caschili et al., 2015), Sweden (Östh, 2011; Östh et al., 2016), and the
 4 Netherlands (Geurs & van Eck, 2003) as well as at an urban scale in Montreal (Cerda, 2009; El-
 5 Geneidy & Levinson, 2011) and Los Angeles (Merlin & Hu, 2017). These studies have shown that
 6 competitive accessibility measures are strongly correlated with non-competitive measures; however,
 7 they have differing spatial distributions and rank orders, which can impact conclusions and specific
 8 policy recommendations. Merlin and Hu (2017) also showed that competitive measures of access to
 9 jobs are a better predictor of employment outcomes than integral measures which do not consider
 10 competition. Despite these few existing studies, the majority of research on access to employment
 11 does not consider competition effects or only considers competition at the destination (i.e. a two
 12 step approach). Up until recently, this is likely due to the computational effort of iterative solutions
 13 in regions with many origins and destinations. Moreover, the majority of existing studies comparing
 14 accessibility between regions do not consider competition effects (Kawabata & Shen, 2006; Grengs
 15 et al., 2010; Levine et al., 2012; Owen & Levinson, 2014; Deboosere & El-Geneidy, 2018). From our
 16 knowledge, only Horner (2004) has used a doubly constrained approach to compare accessibility
 17 between regions (for 10 cities in the United States). The study by Horner (2004) only used distance
 18 as impedance rather than mode-specific travel times and it did not consider unemployed populations
 19 competing for jobs, despite the fact that these variables can differ between regions.

20 Accordingly, we expand upon the measure of competitive accessibility shown in equation (3)
 21 in order to account for regions with different levels of imbalance between origin-constraints (e.g
 22 the size of labour force) and destination-constraints (e.g the number of jobs) as well as differing
 23 transport networks and travel behaviour (e.g. cities have differing levels of transit service as well as
 24 populations with differing mode shares). The following are developed and exemplified for measures
 25 of access to employment, but can be applied to measures to other types of destinations where there
 26 is competition and capacity constraints (e.g. for measuring access to healthcare).

27 **3 Construction of a Comparative Measure**

28 The number of people and the number of opportunities in a region is rarely equal. In terms of access
 29 to employment, the number of job opportunities rarely equals the size of the labour force within a
 30 region. This could be due to workers commuting in and out of the region, unemployed individuals
 31 being part of the labour force who are also competing for jobs, people working multiple jobs, or an
 32 urban economy with an excess of job opportunities that remain unfilled. The accessibility measures
 33 in (3) will not converge given that the total opportunities in the region does not equal the sum of the
 34 population who want to access them (i.e. if $\sum P_i \neq \sum O_j$). To allow for convergence, either O or P
 35 can be scaled so that $\sum O_j = \sum P_i$ prior to computing accessibility in (3). However, the quantity
 36 and spatial distribution of these imbalances are most likely different when comparing between

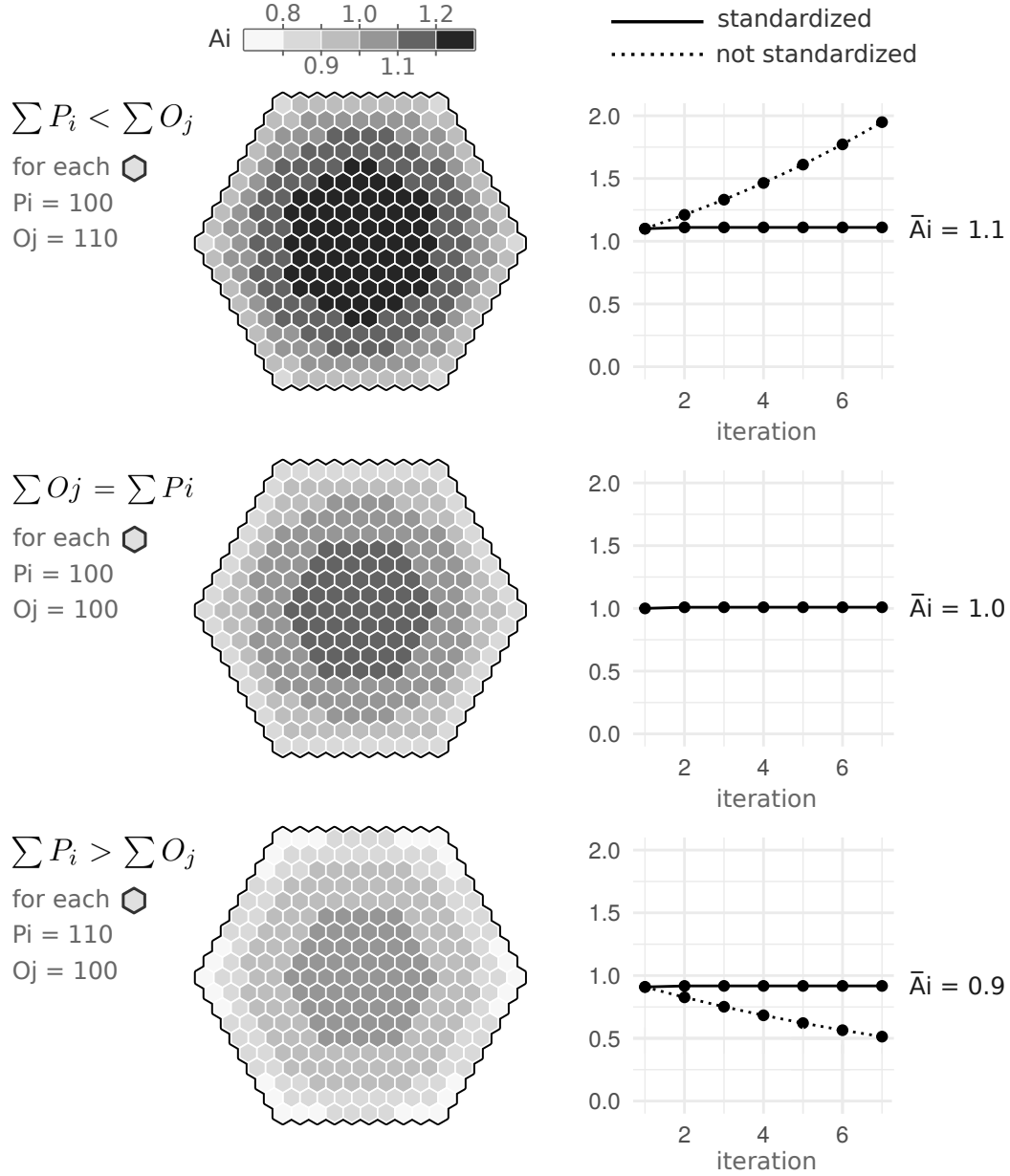
1 cities, and therefore should be accounted for when generating comparative accessibility measures.
 2 So rather than equalizing P or O prior to iterating, we propose that they can be standardized
 3 using the mean accessibility of the population observed after the first iteration. This allows A_i to
 4 be interpretable as an ersatz opportunities per person metric. The equation for A_i is updated as
 5 follows to incorporate this standardization.

$$A_i = \frac{\bar{A}^o}{\bar{A}^c} \sum_{j=1}^J \frac{O_j f(t_{i,j})}{L_j} \quad L_j = \sum_{i=1}^I \frac{P_i f(t_{i,j})}{A_i} \quad (4)$$

$$\bar{A} = \frac{\sum_{i=1}^I P_i A_i}{\sum_{i=1}^I P_i} \quad (5)$$

6 \bar{A}^o is the mean accessibility after the first iteration and \bar{A}^c is the mean accessibility after each
 7 iteration, c . Figure 2 compares three cities of similar urban form, but with different levels of
 8 imbalance; one where there is a greater labour force than the number of jobs $\sum P_i > \sum O_j$ (e.g.
 9 due to unemployment), the second where $\sum P_i = \sum O_j$, and the third where $\sum P_i < \sum O_j$ (e.g.
 10 due to an excess of employment opportunities). These examples are based on the assumption that
 11 there are the same number of population and opportunities in each zone (i.e. perfect jobs-housing
 12 balance) and travel impedance between polygons is consistent across the plane. These figures
 13 indicate how the mean remains stable after each iteration when standardized. The figures also
 14 show how as there are more people competing for jobs, the lower the average level of accessibility in
 15 the region. Running the same simulation with jobs concentrated in the centre (i.e. a mono-centric
 16 urban form) returns similar results, but with a greater range in accessibility from the centre to the
 17 periphery.

Figure 2: Comparing competitive accessibility for three cities with differing imbalance between the population, P , and opportunities, O



- 1 Modal split is another important factor to consider when modelling place-based accessibility.
- 2 In most cities, people travel to work by different travel modes, and compete for jobs within a multi-
- 3 modal labour force (Shen, 1998; Sanchez, Shen, & Peng, 2004). For example, a job at j would be
- 4 more attractive for someone at i , if they have regular access to a private vehicle and the commute
- 5 by car from i to j is faster than the commute by transit. Therefore, we need mode specific measures
- 6 of A_i , and we also need to expand the measure of L_j to account for multiple modes (e.g. the labour
- 7 force that can reach j will be a combination of those who travel by transit and car). This can be

1 accomplished as follows.

$$A_{i,\lambda} = \frac{\bar{A}^o}{\bar{A}^c} \sum_{j=1}^J \frac{O_j f(t_{i,j,\lambda})}{L_j}, \quad L_j = \sum_{\forall \lambda \in \Lambda} \sum_{i=1}^I \frac{\alpha_{i,\lambda} P_i f(t_{i,j,\lambda})}{A_{i,\lambda}}, \quad \sum_{\forall \lambda \in \Lambda} \alpha_{i,\lambda} = 1 \quad (6)$$

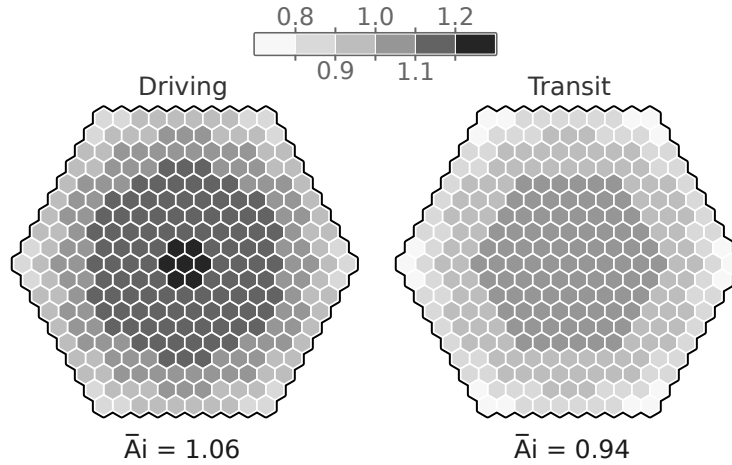
2 Where λ is a travel mode. $\alpha_{i,\lambda}$ is the mode share for travel to work trips of the labour force at
 3 location i and $t_{i,j,\lambda}$ is the travel time from i to j for the mode, λ . The formula for the population
 4 mean level of access is updated to account for multiple modes.

$$\bar{A} = \frac{\sum_{\forall \lambda \in \Lambda} \sum_{i=1}^I \alpha_{i,\lambda} P_i A_{i,\lambda}}{\sum_{i=1}^I P_i} \quad (7)$$

5 The measures of $A_{i,\lambda}$ now depend on the mobility each mode provides relative to other modes,
 6 as well as the mode share for different zones. Figure 3 exemplifies with a case where we assume
 7 that the mode share for each zone is 50% driving and 50% transit and that the impedance function
 8 for travel time to each adjacent zone for transit is 90% than that by driving (i.e. $f(t_T) = 0.9f(t_D)$).
 9 Since mode share is equal across the region in this example, the mean accessibility by transit is
 10 also 90% than that by driving.

Figure 3: Example scenario for comparing competitive accessibility between travel modes.

for each $\hexagon O_j = P_i = 100 \quad \alpha_{i,T} = \alpha_{i,D} = 0.5 \quad f(t_{i,j,T}) = 0.9f(t_{i,j,D})$



11 4 Computing Access to Employment for Canadian Cities

12 The examples in the previous figures are overly simplistic. Real cities have complex transport net-
 13 works and non-uniform spatial distributions of population, employment, and mode share. There-
 14 fore, to further demonstrate the measure presented in (6-7), we compute and compare access to
 15 employment for the eight largest urban regions in Canada. By descending order of population, these

1 are Toronto, Montreal, Vancouver, Calgary, Ottawa, Edmonton, Quebec City, and Winnipeg. For
2 this analysis, we only make use of open-source data and tools in order for the procedure to be
3 replicated and improved upon with minimal cost. This decision does come with some limitations,
4 as congested travel speeds are not available in any open source datasets that we are aware of.

5 The boundaries of the urban regions for our analysis are Census Metropolitan Areas (CMA).
6 CMAs are agglomerations of municipalities which pertain to urban areas with a population of over
7 100,000 in which at least 50% of the employed labour force works in the region's core, as determined
8 from commuting data from the previous census (Statistics Canada, 2016a). Although imperfect,
9 this measurement provides consistency of what constitutes the boundaries of urban regions across
10 Canada. For our analysis, any adjacent CMAs are merged into a single region due to the commuting
11 flows and transit agencies that link adjacent CMAs.

12 For the eight regions, we use 2016 census Dissemination Areas (DA) to model the home
13 locations of the labour force. DAs are the smallest areas in which socio-economic data is available
14 from the quinquennial Canadian census, minimizing error due to the modifiable areal unit problem
15 (see Kwan and Weber (2008) for a discussion of MAUP and its effects in accessibility research).
16 DAs are designed and delineated for populations of 400 to 700 persons (Statistics Canada, 2016a),
17 and have been used in other studies on transit accessibility in Canada (Widener et al., 2017; Wessel
18 et al., 2017). Specifically, we use the population weighted centroids of DAs snapped to the closest
19 walking network segment to model the home locations of residents. Larger, neighbourhood sized
20 Census Tracts (CT), however, are used for the location of employment, as they are the smallest
21 geography in which complete employment data was available for the 2016 census. Since different
22 spatial units were used for the origins and destinations, the issue of self-potential does not apply in
23 our study because we are using two different sets of spatial units to model the demand and supply
24 locations. The issue of self-potential appears when the travel time for the demand and supply
25 within an areal unit is zero (Frost & Spence, 1995). For the few cases where DAs and CTs are
26 the same, a population weighted centroid was used for the origin and the geometric centroid for
27 the destination, so all travel times were greater than zero. It should be noted that several of these
28 urban regions also run their own travel surveys (e.g. the Transportation Tomorrow Survey in the
29 Toronto Region) with home and employment locations of residents, but we required data collected
30 with consistent methodology across the country. Regional travel surveys typically have much more
31 detailed travel diaries, but survey a lower percent of the overall population. The long-form census
32 which we draw our data from is a 25% representative sample of Canadian households.

33 Another primary input into our analysis are travel times between where people live and po-
34 tential places of employment. To compute these travel times, we built custom network graphs for
35 each region. The travel times for driving were computed using the routing engine, Open Source
36 Routing Machine (OSRM) (Luxen & Vetter, 2011), as it includes detailed consideration for driving
37 attributes like speed limits, turn restrictions, and one-way streets. Due to a lack of open-source
38 network level congestion data, travel times for driving were computed as free-flow speeds using

1 OpenStreetMap data, and then multiplied by a congestion factor, k_c , to account for how peak-hour
 2 travel is slower than off-peak. The congestion factors were set at 1.7 for Toronto and Vancouver, 1.6
 3 for Montreal, 1.5 for Ottawa, and 1.4 for the remaining four cities. These values were estimated from
 4 reports examining costs of congestion in Canadian cities (Metrolinx, 2008; Urban Transportation
 5 Task Force, 2012) as well as from TomTom, which hosts an online worldwide ranking of congestion
 6 by city (TomTom, 2018). We also apply a minor two minute penalty for parking, t_p . The peak
 7 hour travel time by driving between two locations, $t_{i,j,d}^*$, is thus calculated from the free flow travel
 8 time, $t_{i,j,d}$ via $t_{i,j,d}^* = k_c t_{i,j,d} + t_p$. Using commercial speed profile data would likely improve the
 9 accuracy of our calculations. However, a secondary objective of our work was to only use data that
 10 was open-source and freely available. Research by Salonen and Toivonen (2013) showed that the
 11 correlation between travel times computed with and without modelling link-level congestion
 12 were 0.98, meaning that the relative differences between auto travel times in each region would
 13 only have slight variation. Therefore, this is a reasonable input for our accessibility measures which
 14 compare auto and transit given that we scale travel times to the mean level of congestion in the
 15 region. As well, there may be some spatial error in using a static exogenous parking parameter.
 16 Central areas may have increased parking times as there are more people searching for a spot, but
 17 conversely peripheral areas have larger surface lots, which can require longer walks from the car to
 18 the work location. As well parking time could also be associated with occupation class or income
 19 level (e.g. high income workers would be more likely to have a spot in their building of employ-
 20 ment, rather using on-street parking). Individual variations in parking time would likely only have
 21 a slight effect on resulting accessibility measures since they are aggregated to areal units.

22 Travel times by transit were computed using the open-source routing engine OpenTripPlanner
 23 (2017). These travel times are inclusive of the time walking to and from stops, wait times, in-
 24 vehicle travels times, and transfers. This has two sets of inputs. The first are the walking networks
 25 in each of these cities from OpenStreetMap. The second are transit schedules in the form of
 26 GTFS (General Transit Feed Specification) data for every transit agency that serves these urban
 27 regions, circa May 2016 in order to align with the collection dates of the 2016 census. We use
 28 these graphs to compute travel time matrices for each of the eight urban regions in our study.
 29 Because of the inherent temporal variations in transit schedules, we follow the precedent in the
 30 literature to compute transit travel times for every minute of the morning commute period (Owen
 31 & Levinson, 2015; Farber & Fu, 2017), to be subsequently averaged when computing accessibility
 32 metrics. Although this is common practice in the literature, taking the average may under-estimate
 33 accessibility as people are likely to select a time that minimizes their commute. For example, it
 34 may make more sense to take the maximum accessibility for 15 minute blocks; but conversely, this
 35 may over-estimate accessibility if this is dependent on transfers which may be possible based on
 36 the schedule data, but unlikely in reality given congestion and bus-bunching during peak periods.
 37 Recent studies have looked at the variation in minute-by-minute accessibility measures (Conway
 38 et al., 2018) and comparing schedule versus real-time (e.g. GPS tracked) measures of accessibility
 39 (Wessel et al., 2017). However more research is likely needed linking travel behaviour outcomes to

1 proper selection of accessibility metrics based on transit schedules. This is not in the scope of our
2 paper, but would be a fruitful direction for future research.

3 For our analysis, we computed travel times in parallel over several processing units which
4 output results for multiple departure times, τ . The outputs are stored in a three-dimensional
5 array, $T_{i,j,\tau} = \{t_{i,j,\tau}\}$, where each cell, $t_{i,j,\tau}$, is the travel time from the origin zone, i , to the
6 destination zone, j , for a specific departure time, τ . Due to heavy computation, travel times were
7 capped at 90 minutes, assuming that no one would be willing to travel to jobs that require more
8 than a 90 minute commute. For our study of Canadian cities, we expand the measure of competitive
9 accessibility presented in (7) to account for a labour force which commutes by car or by transit.
10 This includes averaging transit over the morning commute period (for every minute, τ , from 7:00am
11 to 8:59am) because of temporal variations in transit schedules.

$$A_{i,T} = |120|^{-1} \sum_{\tau \in M} \frac{\bar{A}^o}{\bar{A}^c} \sum_{j=1}^J \frac{O_j f(t_{i,j,\tau})}{L_j} \quad (8)$$

$$A_{i,D} = \frac{\bar{A}^o}{\bar{A}^c} \sum_{j=1}^J \frac{O_j f(t_{i,j,d})}{L_j} \quad (9)$$

$$\bar{A} = \frac{\sum_{\forall \lambda \in \Lambda} \sum_{i=1}^I \alpha_{i,\lambda} P_i A_i}{\sum_{i=1}^I P_i} \quad (10)$$

$$L_j = |120|^{-1} \sum_{\tau \in M} \sum_{i=1}^I \frac{\alpha_{i,T} P_i f(t_{i,j,\tau})}{A_{i,T}} + \sum_{i=1}^I \frac{\alpha_{i,D} P_i f(t_{i,j,d})}{A_{i,D}} \quad (11)$$

12 $A_{i,T}$ is the accessibility measure for transit, and $A_{i,D}$ for driving. $\alpha_{i,D}$ is the commute mode share
13 ratio of workers at location i who travel to work via private vehicle. $\alpha_{i,T}$ is the mode share ratio by
14 transit and walking. The mode share for transit for our study is assumed as the total non-driving
15 commuting population ($\alpha_{i,T} = 1 - \alpha_{i,D}$), and therefore also includes the small percent of those who
16 take active modes (bike or walk). This assumes that those who bike or walk to work are also able
17 to commute to work by transit, but not by car.

18 We did not have accurate flow data in order to calibrate the travel time impedance functions,
19 a practice that frequently occurs in the literature (e.g. Horner, 2004; Caschili et al., 2015). As
20 an alternative, we use a half-life model specification of distance decay to select an exponential
21 decay function parameterized such that the median commute duration returns a value of 0.5 with
22 a maximum value of 1 at $t_{i,j} = 0$ (see Östh et al. (2016) on the use of adopting half-life models for
23 decay functions). 30 minutes is approximately the median commute duration for journey to work
24 trips in Canadian cities (Statistics Canada, 2016b). This results in the following exponential decay
25 function:

$$f(t_{i,j}) = e^{-0.0231 t_{i,j}} \quad (12)$$

1 For thousands of zones, and minute-by-minute travel times, the process for computing multiple
 2 iterations of competitive accessibility is computationally intensive. Therefore, we stopped iterating
 3 when the correlation with the previous iteration was $r > 0.999$. This level of convergence was
 4 reached after 3 or 4 iterations, depending on the city.

5 The results are summarized by region in Table 1 and Figure 4. We tabulate data for both
 6 transit access and auto access, as well as a ratio between transit and auto access, to examine the
 7 differences between these two modes. The complete dataset of accessibility measures, as well as
 8 the code used to compute them, are publicly available on GitHub ([https://github.com/SAUSy-](https://github.com/SAUSy-Lab/canada-transit-access)
 9 [Lab/canada-transit-access](https://github.com/SAUSy-Lab/canada-transit-access)).

Table 1: Summary of results for each urban region for transit (T) and by auto (D)

	Population	Labour Force [†]	Jobs	Mode Share [§]		Mean A_i		Max A_i	
				α_D	α_T	\bar{A}_D	\bar{A}_T	$A_{D,max}$	$A_{T,max}$
Toronto	8,335,444	4,524,570	3,462,100	0.73	0.27	1.00	0.31	1.74	1.16
Montreal	4,098,927	2,189,115	1,756,640	0.69	0.31	1.08	0.31	1.57	0.90
Vancouver	2,745,461	1,498,535	1,091,405	0.72	0.28	0.91	0.39	1.33	1.03
Calgary	1,392,609	816,385	587,280	0.78	0.22	0.85	0.25	1.66	0.72
Ottawa	1,323,783	727,160	595,950	0.72	0.28	1.02	0.34	1.50	0.93
Edmonton	1,321,426	758,150	553,660	0.83	0.17	0.84	0.21	1.15	0.66
Quebec City	800,296	437,325	375,720	0.80	0.20	0.99	0.29	1.29	0.70
Winnipeg	778,489	424,250	344,320	0.79	0.21	0.92	0.39	1.16	0.75
All	20,796,435	11,375,490	8,767,075	0.74	0.26	0.98	0.31	1.74	1.16

[†] Jobs are only those in the region with a "usual place of work" according to the census, while the labour force also includes the unemployed, those who work at home, and those without a fixed place of work.

[§] Mode share for transit is assumed as the total non-driving commuting population ($\alpha_T = 1 - \alpha_D$), and therefore also includes the small percent of those who take active modes (bike or walk)

10 The maximum levels of transit access across the country are observed in central Vancouver
 11 and Toronto. Vancouver has a greater average than Toronto however, likely due to Toronto having
 12 a greater abundance of suburban areas with low transit access, pulling down its regional average.
 13 Montreal is similar in size as Vancouver, but it has a lower mean and maximum level of access by
 14 transit. This can be explained by Montreal having less auto congestion (TomTom, 2018), and a
 15 greater network of private access highways, which expedite travel by car (i.e. car commuters can
 16 compete for more jobs). The mean level of auto access for Montreal is greater than Vancouver
 17 and Toronto. In the Montreal and Toronto regions, each internal municipality typically has its
 18 own transit agency, resulting in poorer intra-regional travel, while the central transit agency in
 19 Vancouver services multiple municipalities (Vancouver, Richmond, Surrey, etc.).

20 Calgary and Edmonton have the lowest averages of access to jobs, both by transit and car. The
 21 urban form of these two cities is more dispersed, and there is greater separation between residential

1 and employment areas. There is also a high concentration of employment in low-density suburban
 2 business parks which have limited transit service and require long walking times from bus stops
 3 to work destinations. The two Albertan cities also had the highest unemployment rates in 2016
 4 compared to the other cities (the unemployment rate was 9.3% in Calgary and 8.5% in Edmonton),
 5 meaning that there are more people competing for jobs, bringing down the overall levels of access
 6 to jobs.

7 Winnipeg has the highest average level of transit accessibility outside the three largest cities.
 8 Winnipeg has fewer peripheral areas with limited transit service, meaning there are fewer areas
 9 pulling down its average, and it does not have any internal motorways which would expedite travel
 10 by car. As well, from visual inspection, it has a greater spatial mix of jobs and housing inside
 11 the city and there is less concentration of employment in suburban business parks. Similar to
 12 Winnipeg, Ottawa and Quebec City have a greater mix of jobs and housing than Calgary and
 13 Edmonton. However, Ottawa and Quebec City are each bisected by a large river with limited
 14 crossings, and different transit agencies operate on either side, limiting accessibility.

15 **5 Comparison of competitive and non-competitive measures**

16 In this section, we examine the correlation between competitive accessibility with non-competitive
 17 measures of accessibility in order to understand how they could lead to different results and con-
 18 clusions. Specifically, we compute Pearson correlation coefficients of competitive accessibility com-
 19 paring with four different types of standard integral measures as in equation (1); the number of
 20 jobs reachable within 30, 45, and 60 minutes, as well as the number of jobs reachable weighted
 21 using the exponential decay function in equation (12). These correlations are computed for transit
 22 accessibility and for auto accessibility and are presented in Table 2.

23 We find very high correlations between the gravity measures of accessibility and the competi-
 24 tive measure of accessibility within each of the eight cities. It is the relative locations of employment
 25 which are the dominant factor in any these accessibility measures. The labour force is more evenly
 26 distributed across each region and accounting for the distribution of the labour force does not ap-
 27 pear to have a substantial effect in comparing competitive to non-competitive accessibility measures
 28 within cities. However, when analyzing all eight cities at the same time, the correlation coefficients
 29 decrease by approximately 0.1 (i.e. when the data for all cities are combined into a single table prior
 30 to computing correlations instead of computing correlations for each individual region). This shows
 31 that for studies analyzing an individual city or region would likely have very minor differences in
 32 results using competitive or non-competitive measures of accessibility, but in a multi-city analysis,
 33 the competitive measure is controlling for relative sizes of the labour force and job opportunities
 34 (e.g. central areas in larger cities have more nearby jobs, but also a larger labour force competing
 35 for these jobs).

36 We also found that transit mode share had a greater correlation with competitive accessibility

1 ($r = 0.82$), than a non-competitive gravity measure of accessibility ($r = 0.80$). However, further
 2 multivariate analysis would be required to see the effects of competition on mode share, as there
 3 are many other land-use and individual-level factors which influence mode share as well.

Table 2: Correlation coefficients between competitive accessibility and four non-competitive accessibility measures, for transit and auto

	Transit				Auto			
	30min	45min	60min	decay*	30min	45min	60min	decay*
Toronto	0.62	0.85	0.94	0.97	0.93	0.92	0.79	0.96
Montreal	0.70	0.89	0.96	0.98	0.96	0.88	0.77	0.99
Vancouver	0.77	0.91	0.96	0.98	0.95	0.89	0.74	0.99
Calgary	0.70	0.87	0.96	0.98	0.90	0.68	0.43	0.99
Ottawa	0.73	0.89	0.97	0.98	0.94	0.81	0.61	0.99
Edmonton	0.74	0.89	0.97	0.98	0.93	0.87	0.71	0.98
Quebec City	0.81	0.90	0.96	0.98	0.86	0.63	0.64	0.99
Winnipeg	0.77	0.91	0.98	0.98	0.88	0.74	0.56	0.99
All	0.66	0.83	0.87	0.89	0.86	0.71	0.50	0.82

* computed using the exponential decay function in equation (12)

4 6 Case Study: Inequalities of Transit Access in Canadian Cities

5 We exemplify a use case of these measures of competitive accessibility by analyzing the spatial
 6 equity of transit access to employment in Canadian cities. Spatial equity can be defined as how
 7 evenly a good or service, like transit provision, is distributed among the overall population over
 8 space (i.e. this does not consider differences by socio-economic status). Specifically, we compute
 9 the Gini coefficient as measure of spatial equity. Delbosc and Currie (2011) and Bertolaccini
 10 and Lownes (2013) have used the Gini to examine the inequalities of nearby transit availability,
 11 while Welch and Mishra (2013) used the Gini in measuring the inequality pertaining to different
 12 aspects of transit connectivity. We use the Gini to measure the inequalities of competitive access
 13 to employment. Table 3 indicates the Gini for each region, by transit and by car. The greater the
 14 values, the greater amount of inequality of access to employment (the Gini ranges from 0 to 1).
 15 Table 3 also compares the results of the competitive measure of accessibility with a non-competitive
 16 measure, both computed using the decay function in (12).

Table 3: Gini coefficients for competitive and non-competitive accessibility*

	Competitive		Non-Competitive	
	Transit	Car	Transit	Car
Toronto	0.43	0.25	0.54	0.35
Montreal	0.39	0.19	0.47	0.22
Vancouver	0.37	0.19	0.42	0.22
Calgary	0.29	0.11	0.36	0.14
Ottawa	0.34	0.17	0.40	0.20
Edmonton	0.36	0.12	0.42	0.17
Quebec City	0.31	0.11	0.38	0.14
Winnipeg	0.24	0.10	0.28	0.12
All	0.40	0.21	0.52	0.38

* all computed using the exponential decay function in equation (12)

1 Overall, there are higher values of inequality for Toronto, Montreal, and Vancouver. These
 2 regions contain extremely high access neighbourhoods located in their downtown cores, which are
 3 within walking distance to major employment centres, as well as rapid and regional transit services
 4 linking to other employment areas. The range in access between their centres and peripheries
 5 results in greater levels of inequality. Smaller cities tend to have more equal levels of access, but
 6 their central areas have lower levels of access than the centres of Toronto, Montreal, and Vancouver.
 7 The larger cities also have a greater abundance of low access suburban areas. Out of the mid-size
 8 cities, Edmonton and Calgary have greater levels of inequality of transit access, while Winnipeg is
 9 the most equitable.

10 It should be noted that the Gini will change depending on the scale of analysis (Bertolaccini
 11 & Lownes, 2013). For example, if we remove suburban municipalities within the region and only
 12 examine the City of Toronto, which has more frequent transit and more transit-oriented develop-
 13 ment, then the resulting Gini coefficient for competitive transit access reduces from 0.43 to 0.15 as
 14 it includes fewer suburban areas with minimal transit service.

15 Table 3 indicates that using non-competitive measures of accessibility result in greater levels of
 16 inequality than competitive measures of accessibility. For the case of Canadian cities, central areas
 17 with high employment concentrations also have higher levels of population density nearby who are
 18 competing for employment. Central areas typically have lower levels of competitive accessibility
 19 than indicated by standard integral measures, while peripheral areas typically have relatively higher
 20 access as there are less people competing for nearby jobs. This reduction in the range of accessibility
 21 results in lower inequality measures, and not accounting for competition can potentially inflate
 22 conclusions of regional transit equity studies.

23 Table 3 and Figure 4 also highlight how there are substantial disparities by travel mode.
 24 Transit accessibility is less than one-third that of auto-accessibility on average. The distribution

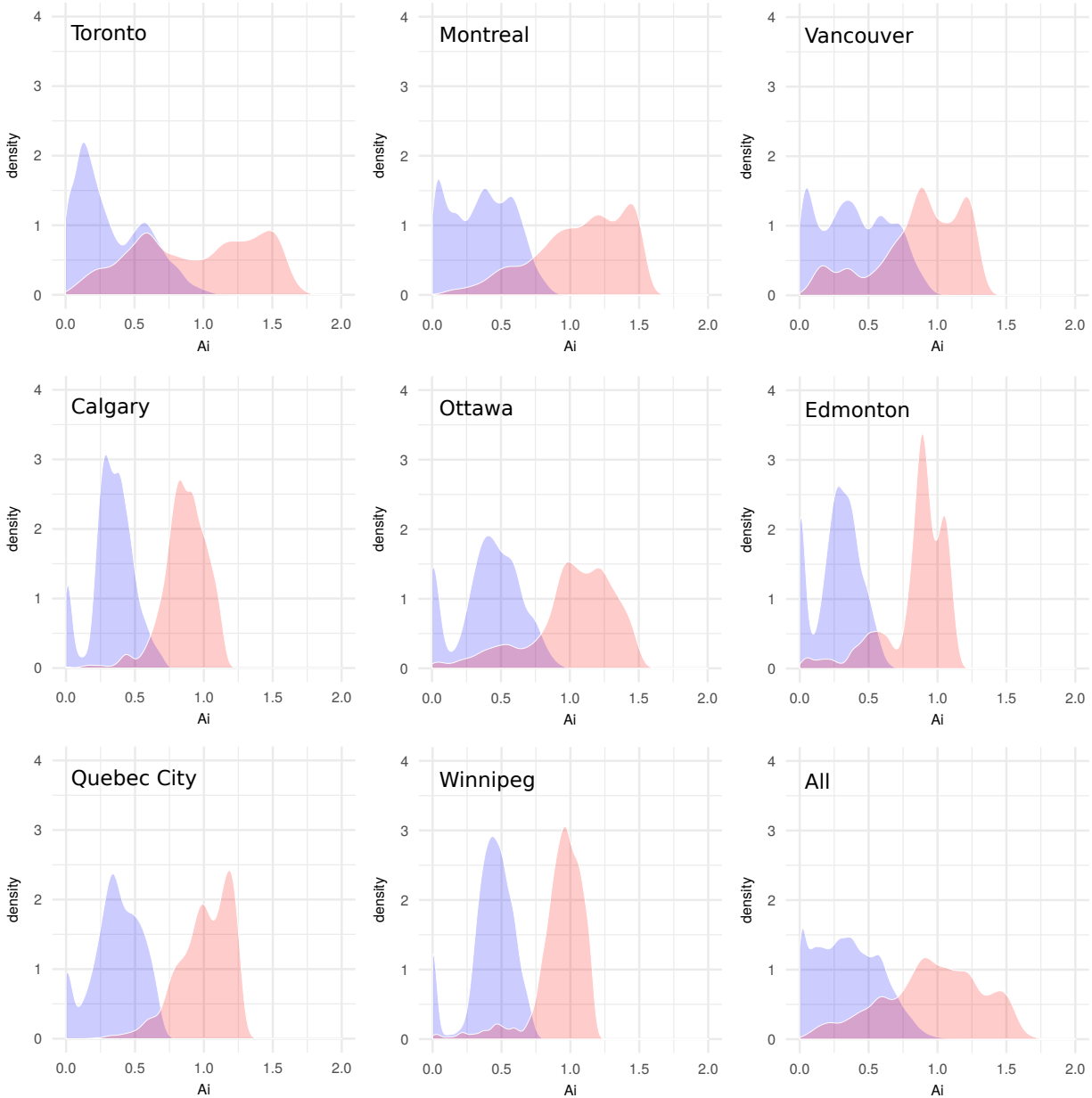
1 of transit access is much more unequal than the distribution of access to jobs by car in each of
2 the eight cities. Transit networks are typically concentrated along certain corridors and are more
3 radially focused compared to regionally dispersed road networks. Many suburban areas have sparse
4 and infrequent transit service, meaning there is a greater share of neighbourhoods at the left of the
5 distributions. Toronto and Vancouver have the greatest overlap of frequency distributions between
6 transit and car. These two cities have high levels of transit accessibility in their centres as well as
7 peripheral communities which are far from the major employment centres which thus have lower
8 levels of auto access. The smaller, more mono-centric cities have less of an overlap between the
9 two travel modes. The gap between transit and auto access also show why suburban areas remain
10 attractive for drivers. When considering competition, especially competition by mode, car drivers
11 in the suburbs are typically doing very well compared to transit users.

12 **7 Conclusion**

13 In this paper, we expanded measures of competitive access to destinations so that they can be
14 used to accurately compare results both within and between cities and by travel mode. There are
15 three primary contributions to methodology being made. First, this formulation uses an iterative
16 process to account for competition among the labour force for jobs, and among employers for
17 potential employees. Second, it is expanded to account for any regional differences in transportation
18 networks and travel modes, by having parameters for mode share and mode specific travel times
19 between origin and destination locations. And third, it standardizes for any imbalance between
20 the size of the population and the number of opportunities in each region, as these values will vary
21 regionally.

22 We used this formulation to generate comparative measures of access to employment for eight
23 Canadian urban regions, and then described how access to employment varies between these regions.
24 We find that at a regional level Vancouver and Winnipeg have the highest average levels of transit
25 based access to jobs, and Calgary and Edmonton have the lowest. The neighbourhoods with
26 the maximum levels of transit access are in central Toronto and Vancouver. We then used these
27 measures to examine how access to jobs is distributed within these regions using Gini coefficients.
28 We find that access is more equally distributed in the smaller cities like Winnipeg and Quebec City,
29 while larger urban areas like Toronto, Montreal, and Vancouver have a greater overall inequality
30 of access to employment. Conducting such analysis with standard integral measures can inflate
31 measures of accessibility when comparing between regions, as raw values are not standardized by
32 the size of the labour force or job market. We also found that standard integral measures can
33 potentially over-estimate the extent of spatial inequities of accessibility.

Figure 4: Frequency distributions of accessibility for each region (blue = transit, red = auto)



1 The application of the formulas presented in this paper examine access to all jobs in a region.
 2 But certainly, not all workers are competing for the same jobs. One direction for future work is to
 3 use the formulations presented in this paper to examine access to employment for specific occupation
 4 classes, industry categories, education, or by income levels. This has been applied in other studies
 5 analyzing inequalities of accessibility (Cervero et al., 1999; Geurs & van Eck, 2003; Fan et al., 2012;
 6 Fransen et al., 2018). At a simple level, this can be formulated by replacing the number of jobs,
 7 O_j , and size of the labour force, P_i , by counts for specific sub-groups (e.g. by occupation class

1 or income level). However, it is certainly possible that people looking for work may not only be
2 competing for jobs within their specified income bracket or occupation class. For example, those in
3 middle-income brackets may also consider lower income jobs if there is dearth of middle-income jobs
4 available, resulting in greater competition for lower-income jobs as well. Future research should
5 examine how to accurately incorporate weights by job type and account for competition across job
6 categories into the formulas presented in this paper. Similarly, we weighted by zonal mode share
7 to estimate the potential of the labour force to access employment opportunities from each zone.
8 However, individuals may have more than one mode available to them, and the extent to which
9 they compete for employment by different modes will be sensitive to individual ability, resources,
10 and preferences (e.g. whether they have a driver's license, monetary cost of travel with respect
11 to income, or sensitivity to longer walking distances to transit stops). More in depth analysis
12 regarding behavioural impacts on competitive accessibility would likely require individual travel
13 behaviour data, rather than the zone-based census data used in this study. The census data used
14 in this study was also limited to the set of all jobs and population within the region, but the
15 distribution of job seekers and job openings could have differing spatial patterns (Fransen et al.,
16 2018). Data for job openings and job seekers is unavailable Canada-wide. If it were available, it
17 would provide the opportunity for more refined accessibility measures as well as a way to validate
18 existing measures.

19 In summary, we recommend that the competitive measure outlined in this paper be used
20 instead of more common non-competitive measures in certain cases, specifically for multi-region
21 studies on analyzing access to employment in which values are being directly compared between
22 cities, or as model parameters for analyses predicting behavioural outcomes like mode share, activity
23 participation rates, or unemployment. Our research also shows how competitive measures can be
24 used to highlight modal inequalities in accessibility. Competitive measures could also complement
25 standard non-competitive measures in guiding land-use regulation or transportation investment.
26 For example, an area with high access using a non-competitive integral measure but with relatively
27 lower access in a competitive measure would be a good location to plan for increased employment
28 density, or further improving the links to employment zones. Lastly, since competitive measures
29 are relatively intuitive as they are presented as opportunities per person, they can be useful for
30 communicating results. Effectively communicating the realities of accessibility, through maps or
31 otherwise, is important for providing evidence for urban planning and policy strategies, as well as
32 increasing the understanding of the transport-land use situation to the general public (Geurs &
33 Van Wee, 2004; Stewart, 2017).

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